

Thank you for choosing **ENDA EM** Series Digital Timer.

-
- EM4401 DIGITAL TIMER
- Out1
Out2
- 26:59 m/s
- Start
Gate
Reset
- OUT MODE
T/A
- 30:00 m/s
- ENDA
- Buttons: [Pencil/Eraser], [Play], [Up Arrow], [Down Arrow]



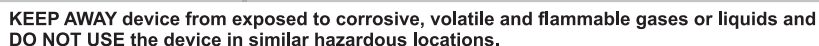
**RoHS
Compliant**



Order Code : EM <div> <div>0</div> <div>1</div> <div>-</div> <div>-</div> <div></div> </div> <div> <div>1</div> <div>2</div> <div>3</div> </div>		
1 - Size 4401.....48x48x87mm 7701.....72x72x97mm	2 - Supply Voltage UV...90-250V AC LV.....10-30V DC / 8-24V AC	3 - Modbus (Optional) RS ...RS-485 (Specify at order)

ENVIRONMENTAL CONDITIONS

Ambient / Storage Temperature	0 ... +50 / ° C -25... +70°C
Relative Humidity	Max. humidity 80% for temperatures up to 31°C decreasing linearly to 50% relative humidity at 40°C.
Protection Class	According to EN60529; Front panel: IP65 Rear panel : IP20
Height	Max. 2000m



ELECTRICAL CHARACTERISTICS

Supply	90-250V AC 50/60Hz ; 10-30V DC / 8-24V AC SMPS
Power Consumption	Max. 5VA
Wiring	2.5mm ² Screw-terminal power connection, 1,5mm ² Terminal plug-in signal connection.
Date Retention	EEPROM (Min. 10 years)
EMC	EN 61326-1: 2013 (Performance criterion B is satisfied for EN 61000-4-3)
Safety Requirements	EN 61010-1: 2010 (Pollution degree 2, overvoltage category II)

INPUTS

Start, Gate, Reset input	<p>Input types can be adjusted as PNP or NPN in "Programming Mode".</p> <p>Minimum pulse and void duration times can be adjusted between 5 and 100ms.</p> <p>Active level is between 4V and 30V pulse in PNP inputs, Active level is between 0V and 2V in NPN inputs.</p>
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OUTPUTS

Control Output OUT1,OUT2	EM4401 : OUT1 : 250V AC, 10A (for resistive load), NO+NC. OUT2 : 250V AC, 5A (for resistive load), NO.
SSR1, SSR2 Output	EM7701 : OUT1, OUT2 : 250V AC, 8A (for resistive load), NO+NC
Auxiliary Power Supply	Open collector output (S.S. OUT) : Max. 30V DC, 50mA. 12V DC, max. 50mA (without regulation).
Life Expectancy for Relay	5.000.000 Switching for no-load operation; 100.000 switching for 5A resistive load at 250VAC. 30.000.000 Switching for no-load operation; 300.000 switching for 8A resistive load at 250VAC. 30.000.000 Switching for no-load operation; 100.000 switching for 10A resistive load at 250VAC.
Accuracy	±0.01% ±1ms



Relay and S.S.OUT outputs run simultaneously. ie, when the OUT 1 or OUT2 relay is energized, the SSR1 or SSR2 transistor also turns on.

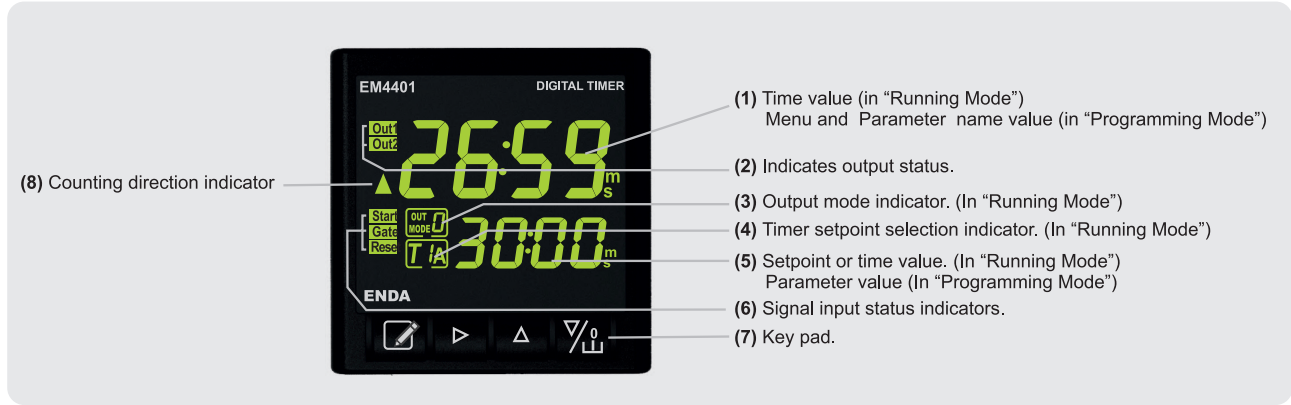
HOUSING

Housing Type	Suitable for flush-panel mounting according to DIN 43 700.
Dimensions	EM4401 : W48xH48xD87mm, EM7701 : W72xH72xD97mm.
Weight	EM4401 : Approx. 230g, EM7701 : Approx. 380g (After packing).
Enclosure Materials	Self extinguishing plastics



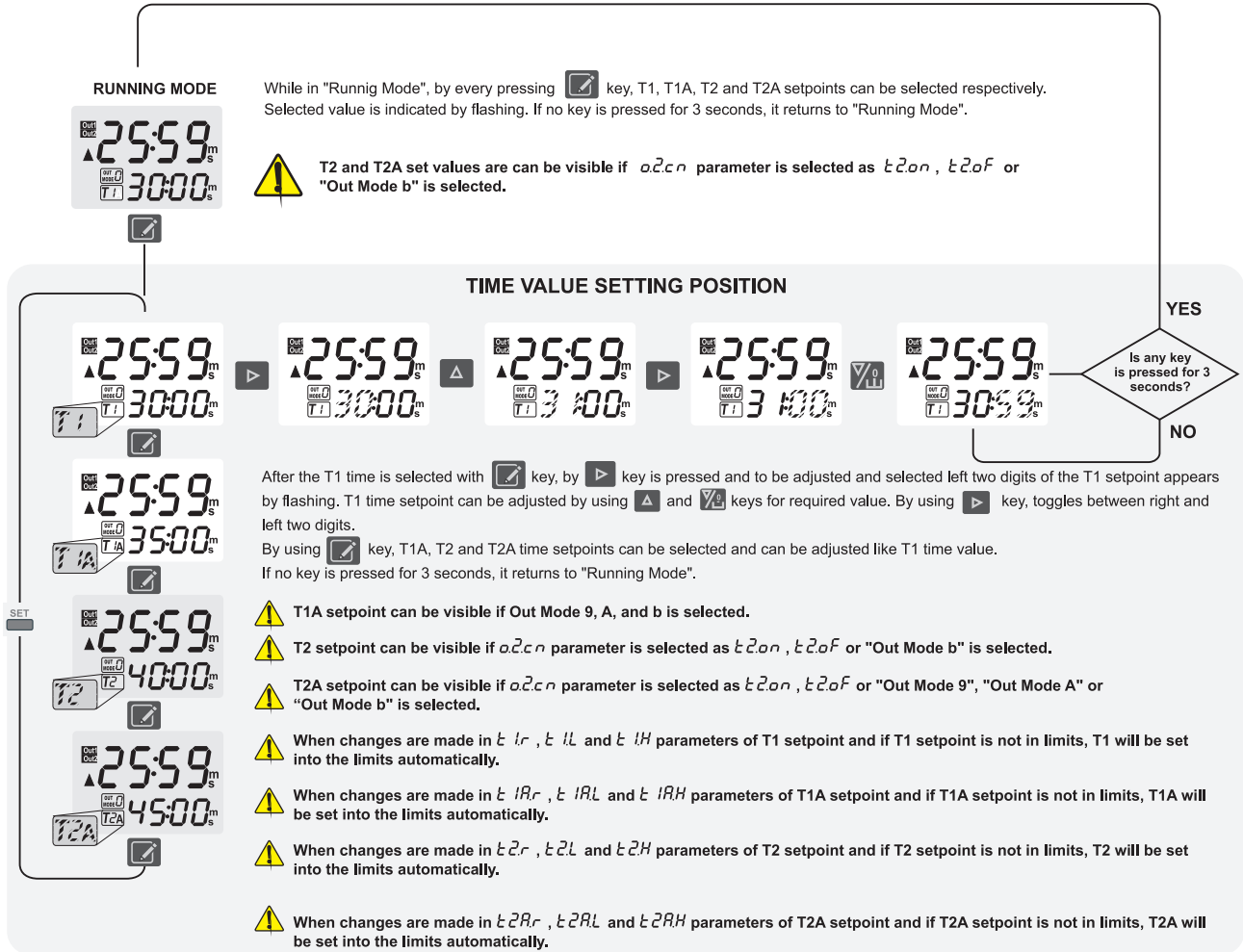
DO NOT clean the device with solvent (thinner, gasoline, acid etc.) and / or abrasive cleaning agents.

TERMS



(1) PV Display	7 Segment, 4 digits green LCD indicator (Character height 10mm)
(5) SV Display	7 Segment, 4 digits green LCD indicator (Character height 7mm)
(2) Output indicators	Two pieces (Green)
(6) Input indicators	Three pieces (Green)
(3) Output mode indicator	Indicates selected output mode number (Green)
(7) Key pad	Micro switch
(4) setpoint information	Indicates setpoint name in SV indicator (Green)

TIME VALUE SETTINGS

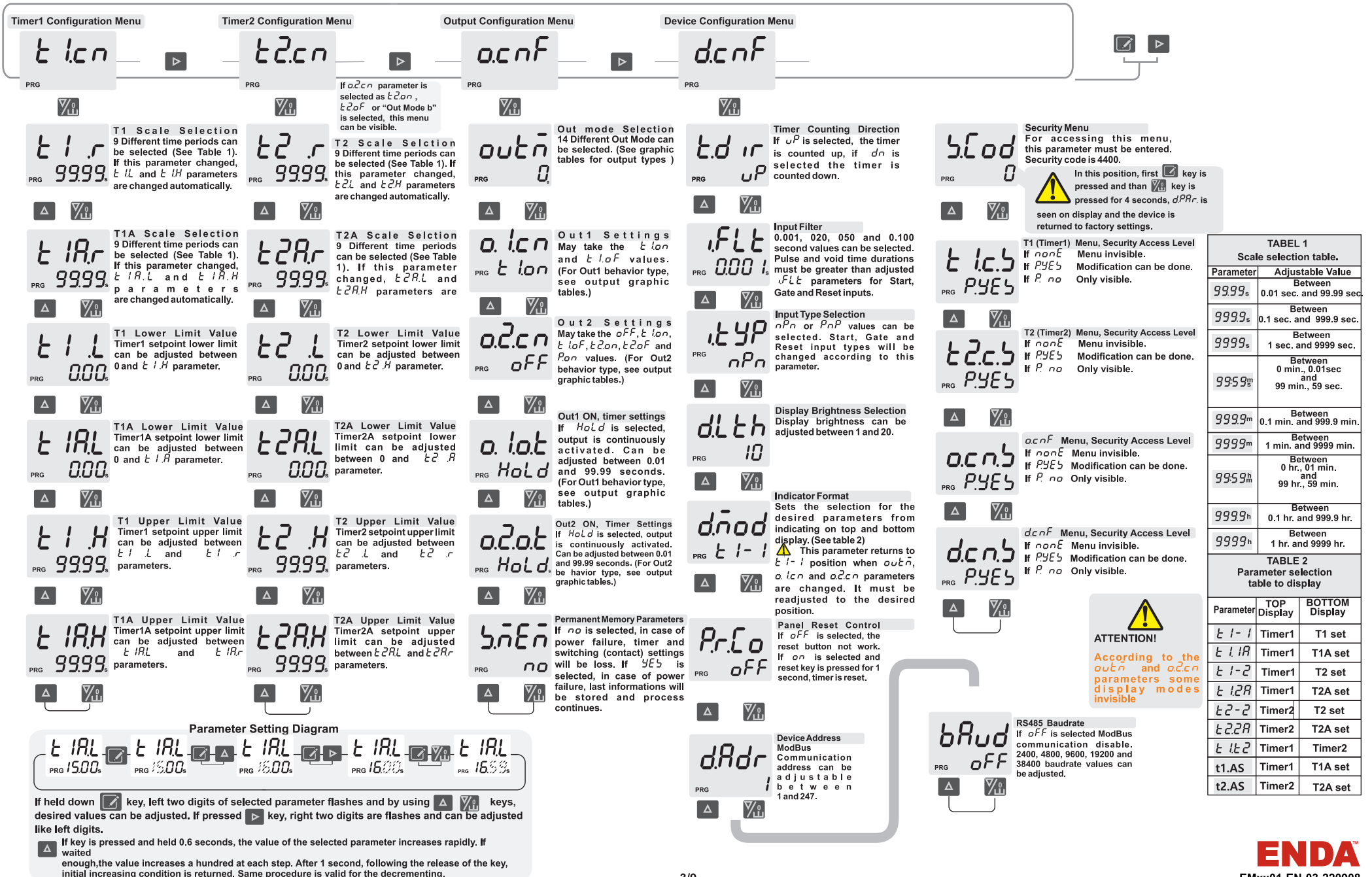


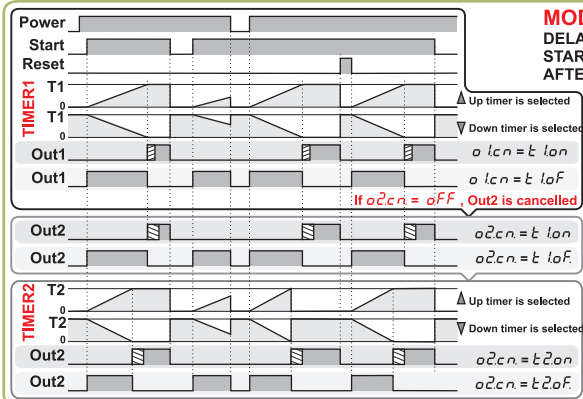
PROGRAMMING DIAGRAM

if key is pressed while holding down to the key, Programming Mode is entered.

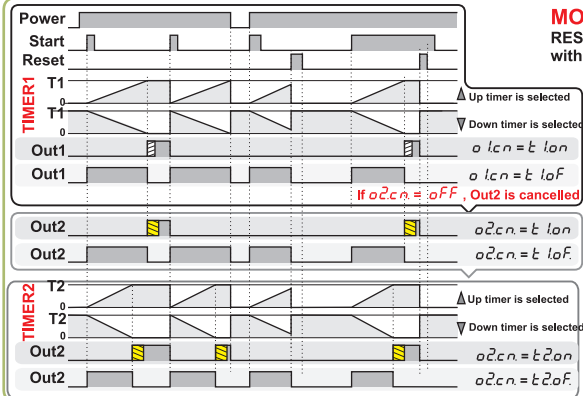
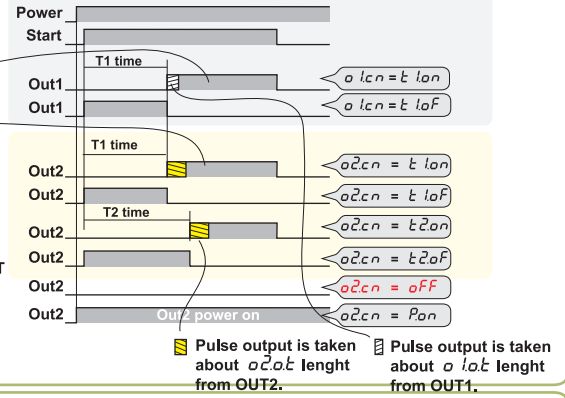
Entering from the Programming Mode to the Running Mode:

If no key is pressed within 20 seconds during Programming Mode, the data is stored automatically and the Running Mode is entered. Alternatively, the same function occurs first pressing key, Programming Mode is entered. Then keys are pressed, data is recorded and "Running Mode" is entered

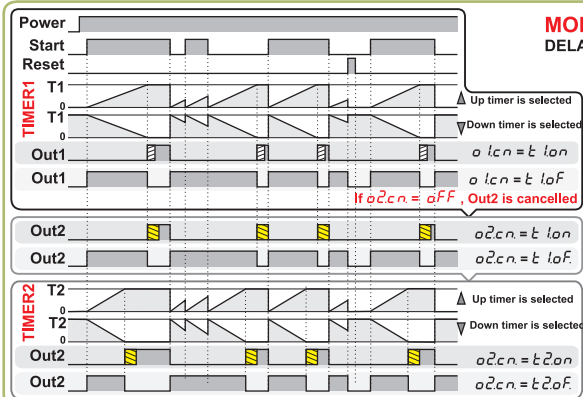
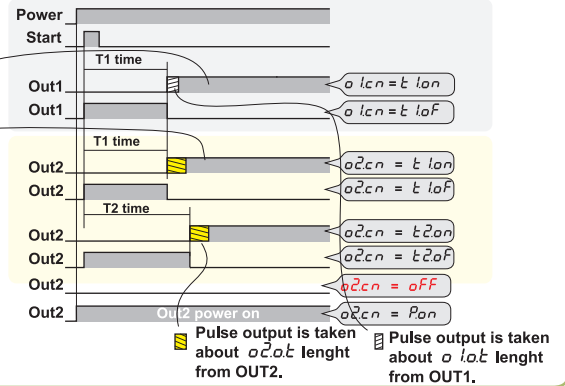




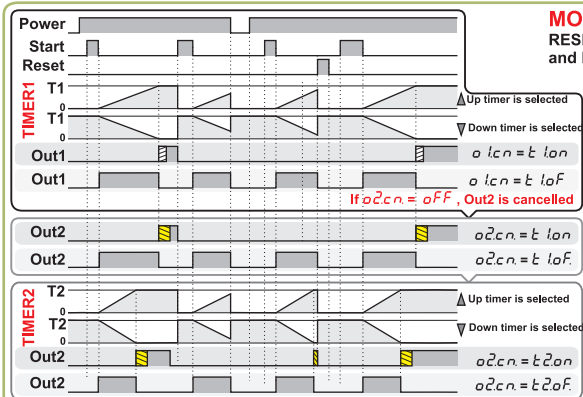
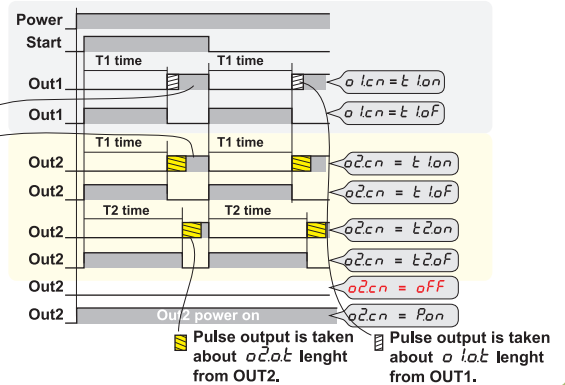
If $o1ot$ or $o2ot$ is selected Hold, output is generated constantly until OFF START Input or RESET Input is taken from OUT1 or OUT2.



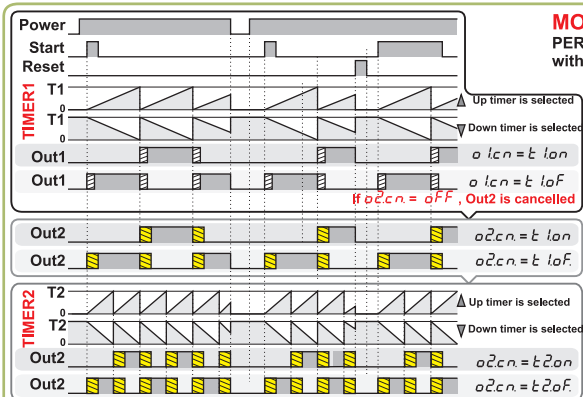
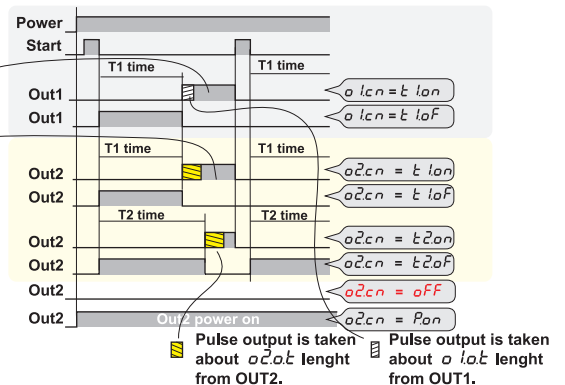
If $o1ot$ or $o2ot$ is selected Hold, output is generated constantly until OFF START Input or RESET Input is taken from OUT1 or OUT2.



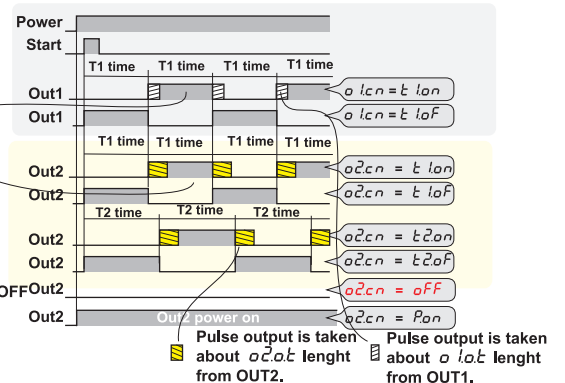
If $o1ot$ or $o2ot$ is selected Hold, output is generated constantly until OFF START Input or RESET Input is taken from OUT1 or OUT2.



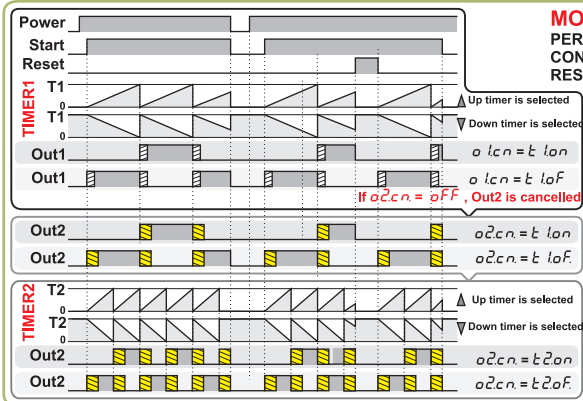
If $o1ot$ or $o2ot$ is selected Hold, output is generated constantly until OFF START Input or RESET Input is taken from OUT1 or OUT2.



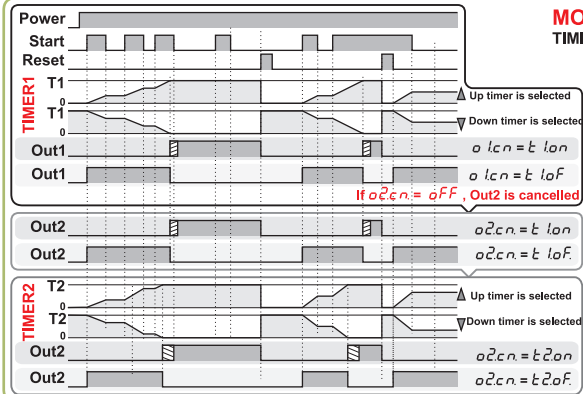
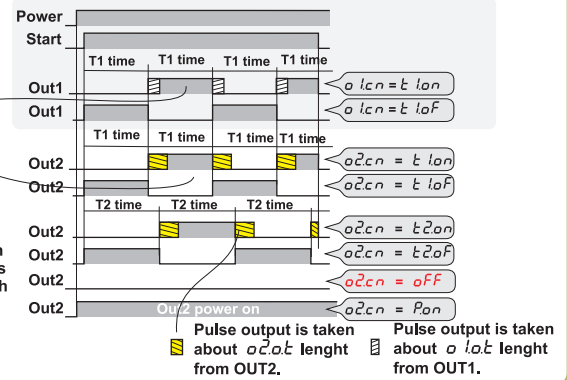
If $o1ot$ or $o2ot$ is selected Hold, Periodically OUT1 is set to ON or OFF with every T1 time, OUT2 is set to ON or OFF with every T2 time.



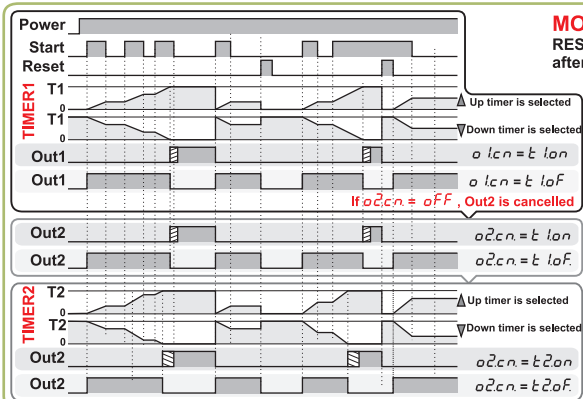
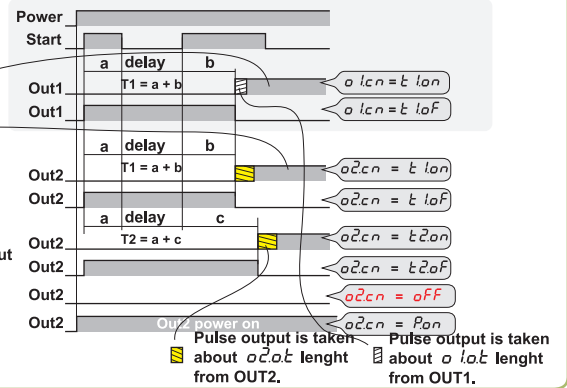
NOTE : All operations will be switched to standby if the Gate input is active.



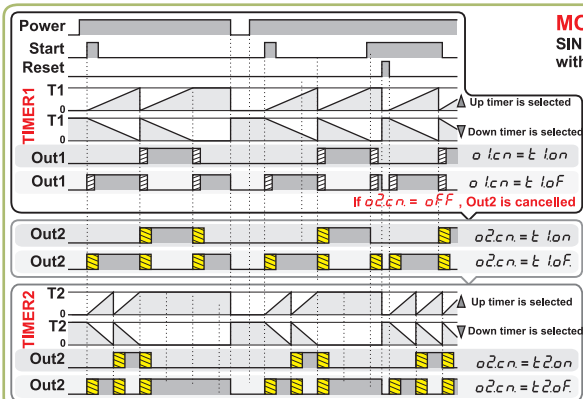
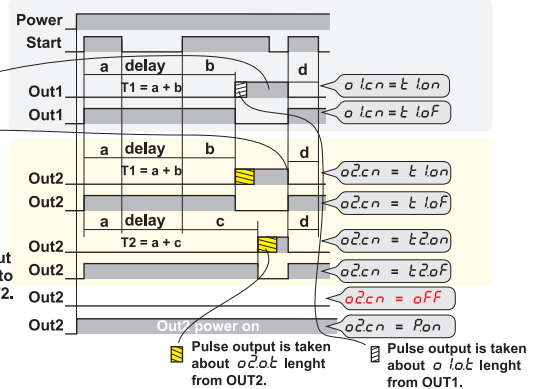
If $o1at$ or $o2at$ is selected Hold, Periodically OUT1 is set to ON or OFF with every T1 time, OUT2 is set to ON or OFF with every T2 time while START signal is ON.



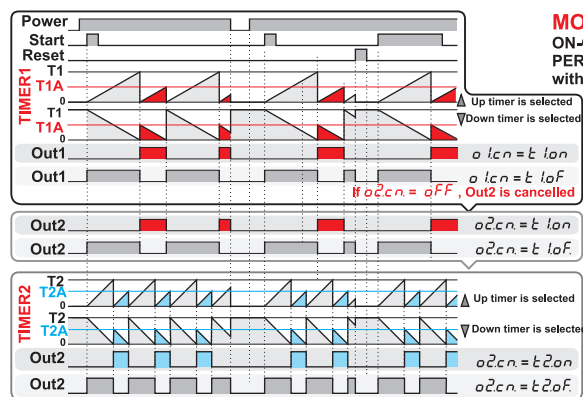
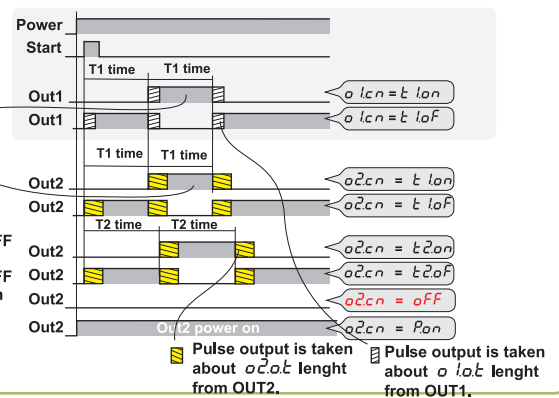
If $o1at$ or $o2at$ is selected Hold, Constant output is taken until RESET Input is set to ON from OUT1 or OUT2.



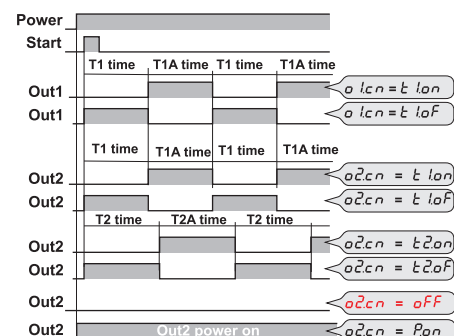
If $o1at$ or $o2at$ is selected Hold, Constant output is taken until START Input or RESET Input is set to ON from OUT1 or OUT2.



If $o1at$ or $o2at$ is selected Hold, OUT1 is set ON or OFF about T1 length, OUT2 is set ON or OFF about T2 length when START Input is set to ON.



ON-OFF TIME
PERIODIC PROCESS
with START PULSE

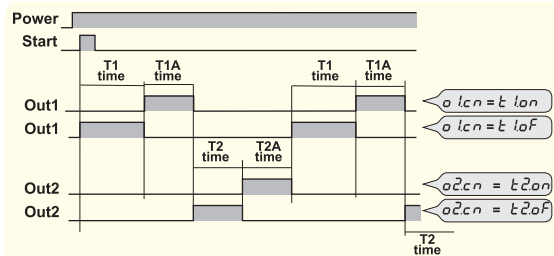
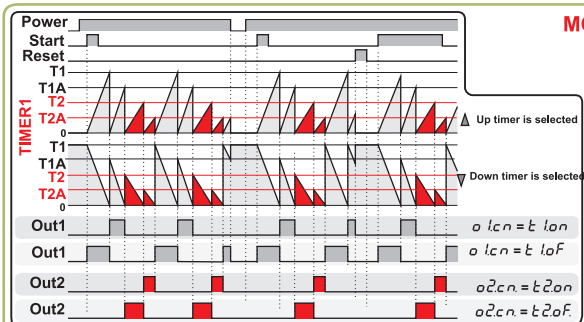
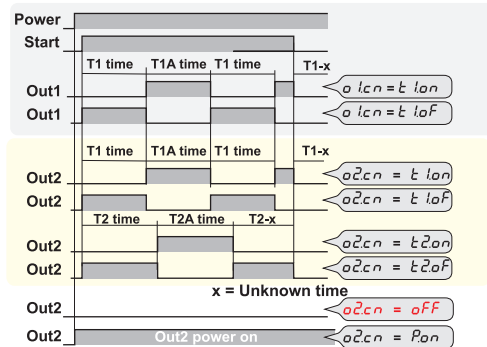
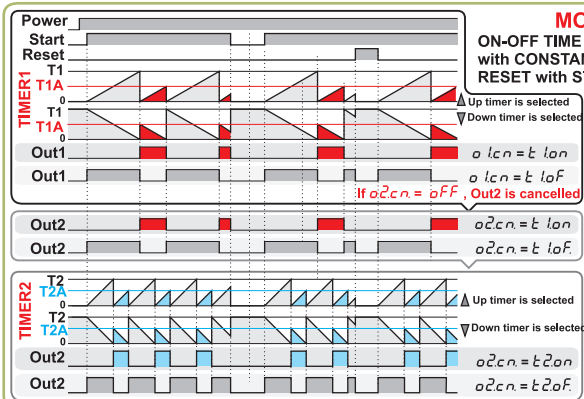


NOTE : All operations will be switched to standby if the Gate input is active.

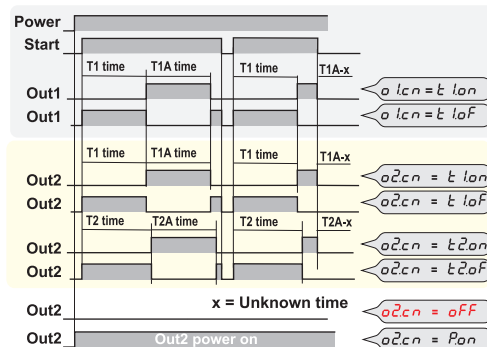
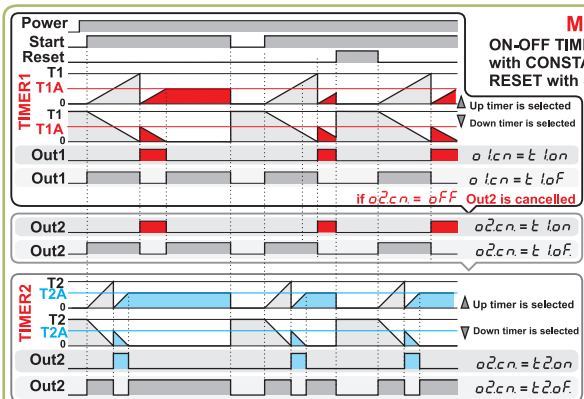
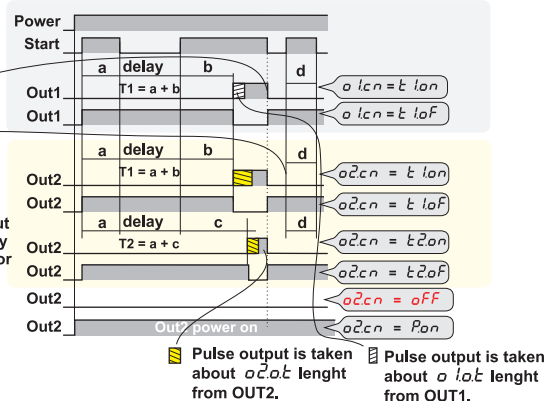
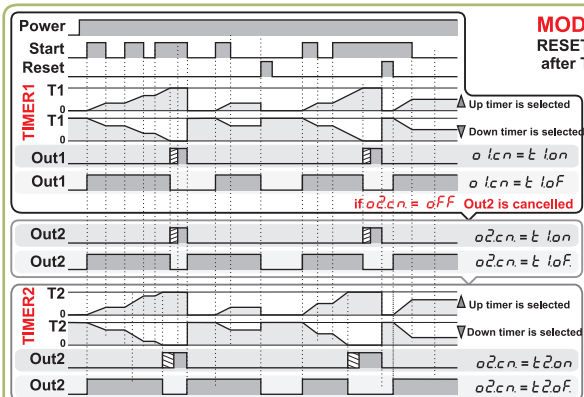
DETAILED EXPLANATION

OUTPUT TYPES GRAPHS - 3

QUICK EXPLANATION



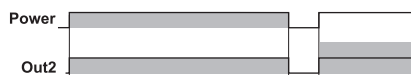
ATTENTION! In order to choose this mode, *o2cn* parameter must be setted to *t2on* or *t2of*.



NOTE 1 : All operations will be switched to standby if the Gate input is active.

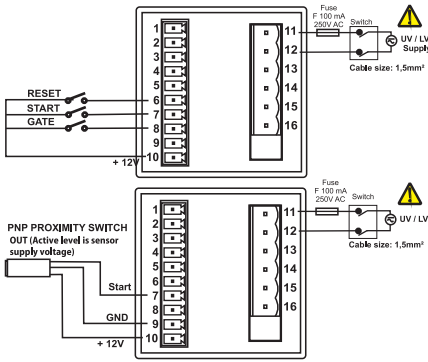
NOTE 2 : If *oc2.cn* parameter is set to *Don* , then Out2 output is activated and remains until power down.

In this selection, the Out2 output is only used to monitor whether the timer is energized. All other Out2 functions cannot be used.

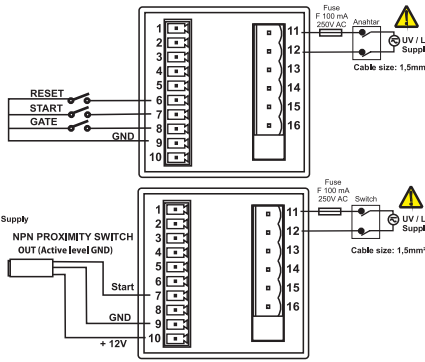


SENSOR CONNECTION SAMPLES

Typical connections for PNP sensor type



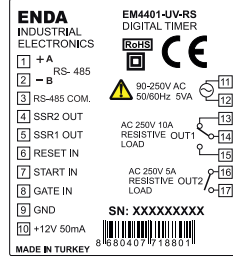
Typical connections for NPN sensor type



Logic output of the device is not electrically isolated. Therefore, the logic output terminals should not be grounded when using grounded thermocouples.

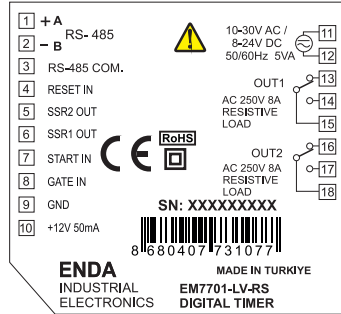
- Note :**
- 1) Mains supply cords shall meet the requirements of IEC60227 or IEC60245.
 - 2) In accordance with the safety regulations, the power supply switch shall bring the identification of the relevant instrument and it should be easily accessible by the operator.

CONNECTION DIAGRAM



Equipment is protected throughout by DOUBLE INSULATION.

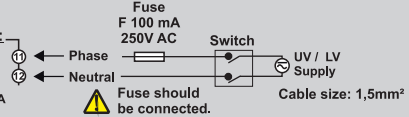
Holding screw 0.4-0.5Nm



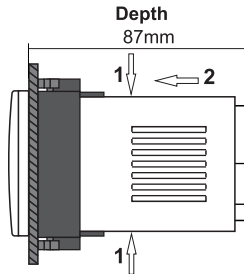
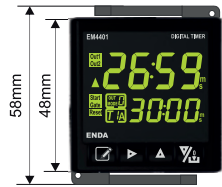
NOTE :

SUPPLY :

90-250V AC
50/60Hz 5VA
10-30V DC/
8-24V AC
50/60Hz 5VA



DIMENSIONS

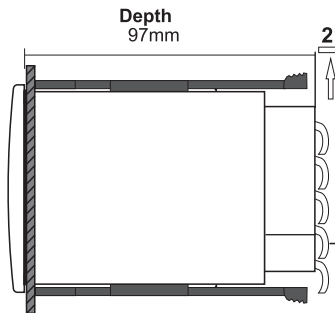
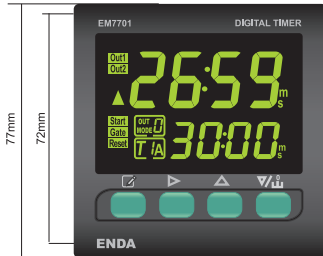


To removing the mounting clamps ;
- Push the device in direction 1 as shown in the figure.
- Then pull out the device in direction 2 .

Connection Cables

Flush mounting clamp

Panel



To removing the mounting clamps ;
- Push the device in direction 1 as shown in the figure.
- Then pull out the device in direction 2 .

Connection Cables

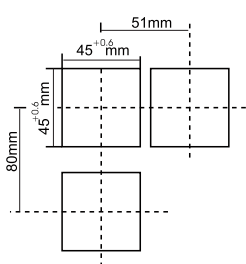
Flush mounting clamp

Panel

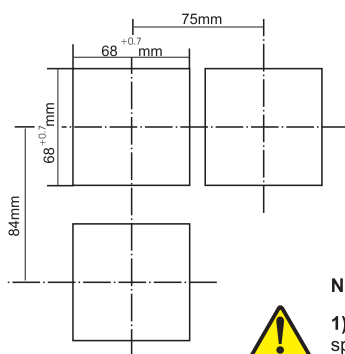
Rubber

PANEL CUT OUT

EM4401



EM7701



Note :

- 1) While performing panel mounting, additional space should be allocated for cables.
- 2) Panel thickness should be maximum 9mm.
- 3) If there is no 100mm free space at back side of the device, it would be difficult to remove it from the panel.



ENDA EM Series is intended for installation within control panels. Make sure that the device is used only for intended purpose. The shielding must be grounded on the instrument side. During an installation, all of the cables that are connected to the device must be free of electrical power. The device must be protected against inadmissible humidity, vibrations, severe soiling. Make sure that the operation temperature is not exceeded. All input and output lines that are not connected to the supply network must be laid out as shielded and twisted cables. These cables should not be close to the power cables or components. The installation and electrical connections must be carried out by a qualified staff and must be according to the relevant locally applicable regulations.

ENDA EM SERIES DIGITAL TIMER MODBUS ADRESS MAP

1.1 Memory Map for Timer Holding Registers

	Parameter Number	Holding Register addresses Decimal (Hex)	Data Type	Data Content	Read / Write Permission	Factory Defaults
Timer1 Configuration Parameters	H0	0000d (0000h)	Word	Setpoint for T1 time (Adjustable between 0-9999d. Format : BCD = 0-9999d) E.g. : Adjusting for 259 seconds MSB = 02h, LSB = 59h	R W	10
	H1	0001d (0001h)	Word	Setpoint for T1A time (Format must be as in the H0 parameter)	R W	15
	H2	0002d (0002h)	Word	Setpoint for T1 time base 0 = 99.99sec, 1 = 999.9sec, 2 = 9999sec, 3 = 99m59sec, 4 = 999.9min 5 = 9999min, 6 = 99h59min, 7 = 999.9hr, 8 = 9999hr.	R W	1
	H3	0003d (0003h)	Word	Setpoint for T1A time base. (Format must be as in the H2 parameter).	R W	0
	H4	0004d (0004h)	Word	Minimum setpoint value limit for T1 time. (Format must be as in the H0 parameter)	R W	0
	H5	0005d (0005h)	Word	Maximum setpoint value limit for T1 time. (Format must be as in the H0 parameter)	R W	9999
	H6	0006d (0006h)	Word	Minimum setpoint value limit for T1A time. (Format must be as in the H0 parameter)	R W	0
Timer2 Configuration Parameters	H7	0007d (0007h)	Word	Maximum setpoint value limit for T1A time. (Format must be as in the H0 parameter)	R W	9999
	H8	0008d (0008h)	Word	Setpoint for T2 time (Format must be as in the H0 parameter)	R W	30
	H9	0009d (0009h)	Word	Setpoint for T2A time (Format must be as in the H0 parameter)	R W	100
	H10	0010d (000Ah)	Word	Setpoint for T2 time base. (Format must be as in the H2 parameter).	R W	1
	H11	0011d (000Bh)	Word	Setpoint for T2A time base. (Format must be as in the H2 parameter).	R W	0
	H12	0012d (000Ch)	Word	Minimum setpoint value limit for T2 time. (Format must be as in the H0 parameter)	R W	0
	H13	0013d (000Dh)	Word	Maximum setpoint value limit for T2 time. (Format must be as in the H0 parameter)	R W	9999
Output Parameters	H14	0014d (000Eh)	Word	Minimum setpoint value limit for T2A time. (Format must be as in the H0 parameter)	R W	0
	H15	0015d (000Fh)	Word	Maximum setpoint value limit for T2A time. (Format must be as in the H0 parameter)	R W	9999
	H16	0016d (0010h)	Word	Outpu type parameter. Can be adjusted between 0 and 11. See graphic tables for output types	R W	0
	H17	0017d (0011h)	Word	OUT1 Configuration parameter. Can be adjusted between 0 and 2. See graphic tables for output types	R W	1
	H18	0018d (0012h)	Word	OUT2 Configuration parameter. Can be adjusted between 0 and 4. See graphic tables for output types	R W	0
	H19	0019d (0013h)	Word	OUT1 Contact output duration. Adjustable between 0.00 and 99.99 sec. (0 = Hold) Format: BCD = 99h, MSB = 99h E.g. : Adjusting for 12.50sec., MSB 12hr, LSB = 50hr	R W	0
	H20	0020d (0014h)	Word	OUT2 Contact output duration. Adjustable between 0.00 and 99.99 sec. (0 = Hold) (Format must be as in the H19 parameter)	R W	0
Device Configuration	H21	0021d (0015h)	Word	Minimum puls duration time parameters for RESET, START and GATE inputs. 0 = 1ms, 1 = 20ms, 2 = 50ms, 3 = 100ms	R W	1
	H22	0022d (0016h)	Word	Display luminous intensity setting parameter. Can be adjusted between 1 and 20.	R W	10
	H23	0023d (0017h)	Word	Display configuration parameter. Adjustable between 0 and 6. See TABLE 2 for selection.	R W	0
	H24	0024d (0018h)	Word	Device address values for Modbus. (Adjustable between 1 and 247)	R W	1
	H25	0025d (0019h)	Word	Communication speed for : 0 = 1200 bps, 1 = 2400 bps, 2 = 4800 bps, 3 = 9600 bps, 4 = 14400 bps, 5 = 19200 bps, 6 = 38400 bps, 7 = 57600 bps	R W	3
Security Parameters	H26	0026d (001Ah)	Word	T1 (Timer1) Menu, security access level parameter. Adjustable between 0 and 2. 0 = Menu invisible, 1 = Modification can be done, 2 = Menu parameters only visible.	R W	1
	H27	0027d (001Bh)	Word	T2 (Timer2) Menu, security access level parameter. Adjustable between 0 and 2. 0 = Menu invisible, 1 = Modification can be done, 2 = Menu parameters only visible.	R W	1
	H28	0028d (001Ch)	Word	Output configuration menu, security access level parameter. Adjustable between 0 and 2. 0 = Menu invisible, 1 = Modification can be done, 2 = Menu parameters only visible.	R W	1
	H29	0029d (001Dh)	Word	Device configuration menu, security access level parameter. Adjustable between 0 and 2. 0 = Menu invisible, 1 = Modification can be done, 2 = Menu parameters only visible.	R W	1
	H30	0030d (001Eh)	Word	Function control parameter. If 23040d (5A00h) value is entered, device is returned to factory settings.	R W	0

1.2 Memory Map for Control Coils

Parameter Number	Coil Addresses Decimal (Hex)	Data Type	Data Content	Read / Write Permission	Factory Defaults
C0	0000d (0000h)	Bit	Timer counting direction (0 = Count UP ,1 = Count DOWN)	R W	0
C1	0001d (0001h)	Bit	Data storage in case of power failure (Permanent memory parameters) 0 = Storing data enabled (Possible), 1 = Storing data disabled (Not Possible).	R W	0
C2	0002d (0002h)	Bit	Sensor type selection. (0 = NPN ,1 = PNP)	R W	0
C3	0003d (0003h)	Bit	Panel RESET activation. (0 = Reset key inactive, 1 = Reset key is active)	R W	0
C4	0004d (0004h)	Bit	Reserve	R W	0
C5-C15	0005d (0005h) 0015d (000Fh)	Bit	Reserve	R W	X

ENDA EM SERIES DIGITAL TIMER MODBUS ADRESS MAP

1.3 Memory Map for Input Registerlers

Parameter Number	Holding Register addresses Decimal (Hex)	Data Type	Data Content	Read / Write Permission
I0	0000d (0000h)	Word	Timer1 time value (Must be read according to BCD format)	R
I1	0001d (0001h)	Word	Timer2 time value (Format is as in the I0 parameter)	R
I2	0002d (0002h)	Word	Out1 puls time value (Must be read according to BCD format. Sensitivity 0.00sn)	R
I3	0003d (0003h)	Word	Out2 puls time value (Format is as in the I2 parameter)	R

1.4 Memory Map for Output Status Indicator Bits

Parameter Number	Discrete input addresses	Data Type	Data Content	Read / Write Permission
D0	(0000)h	Bit	OUT1 Output status (0 = OFF ,1 = ON)	R
D1	(0001)h	Bit	OUT2 Output status (0 = OFF , 1 = ON)	R
D2	(0002)h	Bit	Panel reset key status (0 = Reset key inactive, 1 = Reset key is active)	R
D3	(0003)h	Bit	Reserve	R
D4	(0004)h	Bit	Reset input status (0 = Reset input inactive, 1 = Reset input is active)	R
D5	(0005)h	Bit	Gate input status (0 = Gate input inactive, 1 = Gate input is active)	R
D6	(0006)h	Bit	Start input status (0 = Start input inactive, 1 = Start input is active)	R
D7-D15	0007d (0007h) 0015d (000Fh)	Bit	Reserve	R

1.5 Memory Map for Software Revision Input Registers

Software Revision	0920d (0398h)	14 Word	Software name and update date is in ASCII format and 14 word. Example : EM4401-01 25 March 2016. Memory Format : <table><tr><td>Word</td><td>1</td><td>2</td><td>3</td><td>4</td><td>5</td><td>6</td><td>7</td><td>8</td><td>9</td><td>10</td><td>11</td><td>12</td><td>13</td><td>14</td></tr><tr><td></td><td>M</td><td>E</td><td>4</td><td>4</td><td>0</td><td>1</td><td>0</td><td>-</td><td>1</td><td></td><td></td><td></td><td>5</td><td>2</td></tr><tr><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td>M</td><td>a</td><td>r</td><td>2</td><td>1</td></tr><tr><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td>0</td><td>.</td><td>6</td><td></td></tr></table>	Word	1	2	3	4	5	6	7	8	9	10	11	12	13	14		M	E	4	4	0	1	0	-	1				5	2											M	a	r	2	1												0	.	6		R
Word	1	2	3	4	5	6	7	8	9	10	11	12	13	14																																																		
	M	E	4	4	0	1	0	-	1				5	2																																																		
										M	a	r	2	1																																																		
											0	.	6																																																			
NOTE : To view each word correctly by changing the byte sequences should be displayed as ASCII TEXT																																																																

MODBUS ERROR MESSAGES

Modbus protocol has two types error, communication error and operating error. Reason of the communication error is data corruption in transmission. Parity and CRC control should be done to prevent communication error. Receiver side checks parity and CRC of the data. If they are wrong, the message will be ignored. If format of the data is true but function doesn't perform for any reason, operating error occurs. Slave realizes error and sends error message. Most significant bit of function is changed '1' to indicate error in error message by slave. Error code is sent in data section. Master realizes error type via this message.

ModBus Error Codes

Error Code	Name	Meaning
{01}	ILLEGAL FUNCTION	The function code received in the query is not an allowable action for the slave. If a Poll Program Complete command was issued, this code indicates that no program function preceded it.
{02}	ILLEGAL DATA ADDRESS	The data address received in the query is not an allowable address for the slave.
{03}	ILLEGAL DATA VALUE	A value contained in the query data field is not an allowable value for the slave.

Message Sample ;
Structure of command message
(Byte Format)

Device Address	(0A)h
Function Code	(01)h
Beginning address of coils.	MSB (04)h
	LSB (A1)h
Number of coils (N)	MSB (00)h
	LSB (01)h
CRC DATA	LSB (AC)h
	MSB (63)h

Structure of response message
(Byte Format)

Device Address	(0A)h
Function Code	(81)h
Error Code	(02)h
CRC DATA	LSB (B0)h
	MSB (53)h

As you see in command message, coil information of (4A1)h = 1185 is required but there isn't any coil with 1185 address. Therefore error code with number (02) (Illegal Data Address) sends.

* MODBUS CONNECTION DIAGRAM

